

Elements of rigorous proof of State evolution.

$$A_{ij} = A_{ji} \sim N(0, \frac{1}{n}), \quad A_{ii} \sim N(0, \frac{2}{n}).$$

$$A \sim \text{GOE}(n).$$

$$\text{AMP: } \begin{cases} x^{t+1} = A m^t - b_t \cdot m^{t-1} \\ m^t = f_+(x^t), \quad b_t = \frac{1}{n} \sum_{i=1}^n f'_t(x_i^t) \end{cases}$$

$$\text{Init: } m^{-1} = 0, \quad x^0 \in \mathbb{R}^n. \quad \frac{1}{n} \sum_{i=1}^n \delta_{x_i^0} \rightarrow \mathbb{P}_0 = \langle f'_t(x^t) \rangle.$$

- The empirical dist $\frac{1}{n} \sum_{i=1}^n \delta_{x_i^0} \rightarrow \mathbb{P}_0$ has mean, finite second moment.
- f_t is Lipschitz w.t.

State evolution: For any $\phi: \mathbb{R}^{t+1} \rightarrow \mathbb{R}$ pseudo-Lipschitz then

$$\frac{1}{n} \sum_{i=1}^n \phi(x_i^0, \dots, x_i^t) \xrightarrow[n \rightarrow \infty]{\mathbb{P}} \mathbb{E} \phi(Z^0, \dots, Z^t).$$

where $Z^0 \sim \mathbb{P}_0$, (Z^1, \dots, Z^t) is a Gaussian vector centered, covariance defined

recursively:

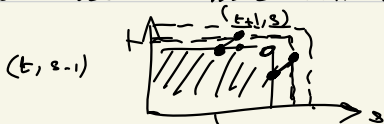
$$\forall t, s \geq 0 \quad \mathbb{E} [Z^{t+1} \cdot Z^{s+1}] = \mathbb{E} [f_t(Z^t) \cdot f_s(Z^s)].$$

Z^0 and (Z^1, \dots, Z^t) are independent.

$$\begin{aligned} \text{E.g. } s=0: \quad \mathbb{E} [Z^{t+1} \cdot Z^0] &= \mathbb{E} [f_t(Z^t) \cdot f_0(Z^0)] \\ &= \mathbb{E} [f_t(Z^t)] \cdot \mathbb{E} [f_0(Z^0)] \end{aligned}$$

(under independence)

The covariance matrix is well defined by induction



• If ϕ depends only on (x_i^t) , then

$$\frac{1}{n} \sum_{i=1}^n \phi(x_i^t) \rightarrow \mathbb{E} \phi(z^t).$$

$$z^t \sim N(0, \Sigma_t^z).$$

$$\begin{aligned} \Sigma_{t+1}^z &= \mathbb{E} [(z^{t+1})^2] = \mathbb{E} [f_t(z^t)^2] \\ &= \mathbb{E} [f_t(\sigma_t \cdot \xi)^2], \quad \xi \sim N(0, 1). \end{aligned}$$

Proof technique: Gaussian conditioning.

Instead of asking about dist of x^{t+1} given past iterates, we ask ^{about} the dist of A given the past iterates.

$$1 \leq t \leq T-1: A m^t = x^{t+1} + b_t m^{t-1} = y^t \quad (*)$$

$$\mathcal{F}_t = \sigma(x^1, \dots, x^t).$$

m^0, \dots, m^t are \mathcal{F}_t -measurable.

$$b^0, \dots, b^t \text{ ————— }$$

Conditional on $\mathcal{F}_T \setminus \{m^t, y^t\}_{t=1}^T$ are known,

$A|_{\mathcal{F}_T}$ is equivalent to conditioning A

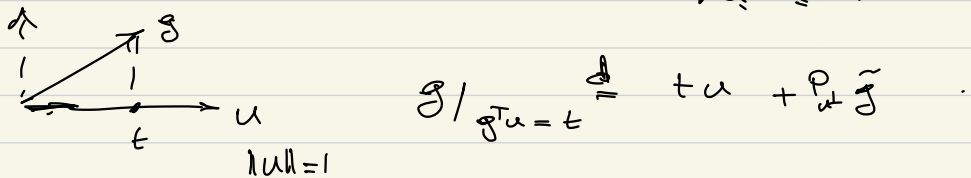
on the linear system $(*)$: $A m^t = y^t$
 $\forall 0 \leq t \leq T-1.$

Since A is gaussian :

$$A | \mathcal{F}_t \stackrel{d}{=} \mathbb{E}[A | \mathcal{F}_t] + \mathcal{P}_t(\tilde{A}), \tilde{A} \stackrel{d}{=} A \text{ indep}$$

where \mathcal{P}_t is the orthogonal projector onto

the subspace $\left\{ A \in \mathbb{R}^{n \times n} : A = A^T, A m^t = 0 \right\}$
 $\forall 0 \leq t \leq T-1$



write the AMP iteration :

$$\begin{aligned} x^{t+1} | \mathcal{F}_t &\stackrel{d}{=} A | \mathcal{F}_t m^t - b_t m^{t-1} \\ &= \mathbb{E}[A | \mathcal{F}_t] m^t + \mathcal{P}_t(\tilde{A}) m^t - b_t m^{t-1} \\ &= \tilde{A} m^t + \underbrace{(\mathcal{P}_t(\tilde{A}) - \tilde{A}) m^t}_{\text{Gaussian}} + \mathbb{E}[A | \mathcal{F}_t] m^t - b_t m^{t-1} \\ &= \underbrace{\tilde{A} m^t}_{\text{Gaussian}} - \underbrace{\mathcal{P}_t(\tilde{A}) m^t}_{\parallel \rightarrow 0} + \mathbb{E}[A | \mathcal{F}_t] m^t - b_t m^{t-1} \end{aligned}$$

$\mathbb{E}[A | \mathcal{F}_t] m^t$ and $b_t m^{t-1}$ will nearly cancel out.

$\Rightarrow x^{t+1} | \mathcal{F}_t$ is Gaussian centered.

by induction : (x^0, \dots, x^t) is centered Gaussian

$$\frac{1}{n} \langle x^{t+1}, x^{s+1} \rangle = \frac{1}{n} \langle \tilde{A} m^t, \tilde{A} m^s \rangle \approx \frac{1}{n} \langle m^t, m^s \rangle$$

$$= \frac{1}{n} < f_t(x^t), f_t(x^s) >$$

• The actual proof: The Long AMP (LAMP)
Berthier - Montanari - Nguyen 2017.

$$\begin{cases} h^{t+1} = P_{t-1}^\perp A P_{t-1}^\perp q^t + \underbrace{H_{t-1}} \alpha^t \\ q^t = f_t(h^t), \quad \sum_{s=0}^t \alpha_{s-1}^t h^s \end{cases}$$

$$\text{init: } h^0 = x^0, \quad h^1 = A q^0 = A f_0(h^0)$$

$$Q_{t-1} = [q^0 \mid \dots \mid q^{t-1}] \in \mathbb{R}^{n \times t}$$

$$P_{t-1} = \text{orthogonal proj onto } \text{Span}(q^0, \dots, q^t)$$

$$= Q_{t-1} (Q_{t-1}^\top Q_{t-1})^{-1} Q_{t-1}^\top$$

$$H_{t-1} = [h^1 \mid \dots \mid h^t] \in \mathbb{R}^{n \times t}$$

$$\alpha^t = \underset{\alpha \in \mathbb{R}^t}{\text{argmin}} \left\| q^t - \sum_{s=0}^{t-1} \alpha_s q^s \right\|_2^2$$

i.e.:

$$q_{\parallel}^t = \text{Proj of } q^t \text{ on } \text{Span} \{ q^0, \dots, q^{t-1} \}$$

$$= P_{t-1} q^t = \sum_{s=0}^{t-1} \alpha_s^t q^s$$

Proposition 1:

LAMP and AMP trajectories are close:

$$\begin{cases} \frac{1}{\sqrt{n}} \| h^{t+1} - x^{t+1} \|_2 \xrightarrow{P} 0 & \forall t \\ \frac{1}{\sqrt{n}} \| q^t - m^t \|_2 \xrightarrow{P} 0 & \forall t \end{cases}$$

Proposition 2: Geometry of iterates of LAMP:

1. $\forall t \geq 1, 1 \leq r, s \leq t$:

$$\frac{1}{n} \langle h^{r+1}, h^{s+1} \rangle \xrightarrow{P} \frac{1}{n} \langle q^r, q^s \rangle.$$

$a_n \xrightarrow{P} b_n$ means $a_n - b_n \rightarrow 0$ in prob.

$$e_0 \quad \frac{1}{n} \sum_{i=1}^n \phi(h_i^0, \dots, h_i^t) \xrightarrow[n \rightarrow \infty]{P} \mathbb{E} \phi(Z^0, \dots, Z^t)$$

(Z^0, \dots, Z^t) has the same law as in SE theorem.

Proposition 3:

$$h^{t+1} / \mathcal{F}_t \stackrel{d}{=} P_{t-1}^\perp A^{\text{new}} P_{t-1}^\perp q^t + H_{t-1} \alpha^t.$$

$$\mathcal{F}_t = \sigma(h_i^0, \dots, h_i^t). \quad A^{\text{new}} \stackrel{d}{=} A, \text{ indep of } A.$$

Proof of Prop 3:

$$q_\perp^t = P_{t-1}^\perp q^t$$

$P_{t-1} = \text{Proj onto span}\{q^0, \dots, q^{t-1}\}$

$$\tilde{\mathcal{F}}_{t-1} = \sigma(q_\perp^0, \dots, q_\perp^{t-1}).$$

$$\tilde{P}_{t-1} = \text{Proj onto span}\{q_\perp^0, \dots, q_\perp^{t-1}\}$$

$$= P_{t-1}.$$

$$q_\perp^0 = q^0$$

$$\begin{aligned}
 h^{t+1} &= P_{t-1}^\perp A P_{t-1}^\perp q_\perp^t + H_{t-1} \alpha^t \\
 &= \tilde{P}_{t-1}^\perp A \tilde{P}_{t-1}^\perp q_\perp^t + H_{t-1} \alpha^t.
 \end{aligned}$$

We have $\tilde{P}_{t-1}^\perp = \tilde{Q}_{t-1} (\tilde{Q}_{t-1}^\top \tilde{Q}_{t-1})^{-1} \tilde{Q}_{t-1}^\top$.

Consider the term $A \tilde{Q}_{t-1} = \left[A q_\perp^s \right]_{s=0}^{t-1}$ which shows up in $A \tilde{P}_{t-1}^\perp$.

Let $y^t = A q_\perp^t$.

• want to argue that y^{t-1} is \mathcal{F}_t -measurable.

$$y^t = A q_\perp^t$$

$$h^{t+1} = \tilde{P}_{t-1}^\perp A q_\perp^t + H_{t-1} \alpha^t$$

$$= (I - \tilde{P}_{t-1}) A q_\perp^t + H_{t-1} \alpha^t.$$

$$= y^t - \tilde{P}_{t-1} A q_\perp^t + H_{t-1} \alpha^t.$$

$$\Rightarrow y^t = h^{t+1} + \tilde{P}_{t-1} A q_\perp^t - H_{t-1} \alpha^t.$$

$$\begin{aligned}
 &= h^{t+1} + \tilde{Q}_{t-1} (\tilde{Q}_{t-1}^\top \tilde{Q}_{t-1})^{-1} \tilde{Q}_{t-1}^\top A q_\perp^t - H_{t-1} \alpha^t. \\
 &\qquad\qquad\qquad = \gamma_{t-1}^\top
 \end{aligned}$$

where we define

$$\gamma_{t-1} = [y^1 \dots y^{t-1}]^\top.$$

Therefore, by induction, y^t is \mathcal{F}_{t+1} -measurable.

\Rightarrow conditioning A on the past i.e. $\mathcal{G}_t = \sigma(h^1, \dots, h^t)$

is equivalent to conditioning A on

$$A \mid \mathcal{G}_t^s = y^s \quad 0 \leq s \leq t-1.$$